



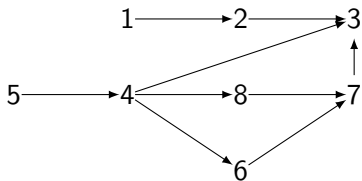
# A Comparison of Random Task Graph Generation Methods for Scheduling Problems

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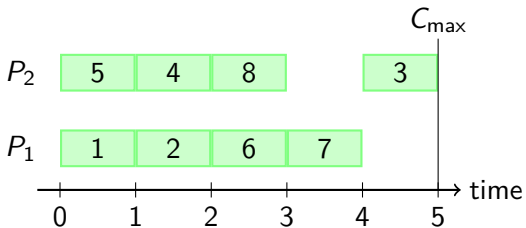
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# Directed Acyclic Graph (DAG)





$$P | p_j = 1, prec | C_{\max}$$





# Random Generation

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## Validation Approaches:

- ▶ Formal analysis
- ▶ Simulation on actual traces
- ▶ Experimentation in real environments
- ▶ Emulation
- ▶ Validation on random instances

## Random generation:

- ▶ Allows comparing strategies on many diverse situations
- ▶ May be biased (instances that are not representative of the whole space)



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# Uniformity

Isom. classes	Matrices	ER	Labeling
	$\begin{pmatrix} 0 & 0 \\ 0 & 0 \end{pmatrix}$	$\frac{1}{8}$	1
	$\begin{pmatrix} 1 & 0 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 1 \\ 0 & 0 \end{pmatrix} \begin{pmatrix} 0 & 0 \\ 0 & 1 \end{pmatrix}$	$\frac{3}{8}$	6
	$\begin{pmatrix} 0 & 1 \\ 0 & 1 \end{pmatrix}$	$\frac{1}{8}$	3
	$\begin{pmatrix} 1 & 1 \\ 0 & 0 \end{pmatrix}$	$\frac{1}{8}$	3
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## Related Work

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- Methods** uniform generation (1973), layer-by-layer (1974), etc.
- Real-cases** LU/QR/Cholesky decomposition, parallel Gaussian elimination algorithm, parallel Laplace equation, etc.
- Data sets** PSPLIB (1995), TGFF (1998), STG (2002).
  - Tools** DAGGEN (2009), GGen (2010), Pegasus workflow generator (2013), etc.



## Existing Generation Methods

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We focus on four methods:

**Uniform** Uniform generation among the labeled DAGs

**Erdős-Rényi** Uniform generation among the adjacency matrices

**Random orders** Combination of random orders

**Layer-by-Layer** Ad hoc methods enforcing “layers”



## Sub-Exponential Algorithm (Uniform Instances)



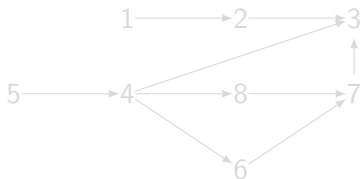
- ▶ Decompose an instance of size  $n$  into many small sub-problems ( $m$ )
- ▶ Apply exponential brute force approach to solve each sub-problems ( $O(2^m)$ )
- ▶ If each sub-problem size is small ( $m = O(\log(n))$ ), then the strategy is polynomial
- ▶ If each sub-problem size is “quite” small ( $m = O(\log^k(n))$ ), then the strategy is sub-exponential



# Shape

Shape decomposition  $(X_1, X_2, \dots, X_k)$ :  $X_i$  contains all vertices of depth  $i$ .

Example



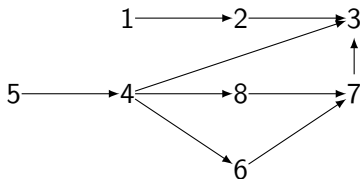
$(\{1, 5\}, \{2, 4\}, \{8, 6\}, \{7\}, \{3\})$



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## Example



$(\{1, 5\}, \{2, 4\}, \{8, 6\}, \{7\}, \{3\})$

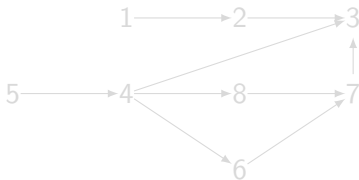


# Mass

If  $|X_i| = 1$ , then all predecessors can be scheduled independently of the successors.

The (absolute) *mass* is the maximum number of vertices that cannot be decomposed (the size of the largest sub-problem).

## Example



The mass is 6.

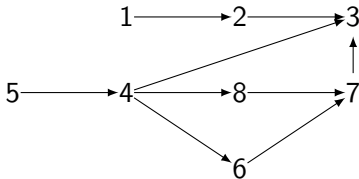


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## Generic-case Complexity

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Complexity on most inputs.

### Theorem

*Let  $D$  be a DAG uniformly and randomly generated among the labeled DAGs with  $n$  vertices. One has*

$\Pr(\text{mass}(D) \geq \log^4(n)) \rightarrow 0$  when  $n \rightarrow +\infty$ .

## Length and Width of Largest Sub-Problem

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Length (shape length):

### Lemma

For every  $n > 0$ ,  $\Pr(\ell_{\max} \geq \ell) \leq n(1 - \alpha_0)^\ell$ .

Width (maximum shape):

### Proposition

One has  $E(\max(x_i)) = O(\log n)$ .

## Uniformity over a Subspace

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Uniform generation among instances with maximum mass ( $= n$ ).  
Which other characteristics should be constrained?





## DAG Properties

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- ▶ number of vertices
- ▶ number of edges
- ▶ maximum/minimum/mean/sd out/in/total degree
- ▶ length
- ▶ width
- ▶ maximum/minimum/mean/sd shape
- ▶ equivalent properties on the reverse shape
- ▶ equivalent properties on the transitive reduction



# Simple DAGs Properties

DAG	len	$m$	$m(D^T)$	mass	shape <sup>mean</sup>	shape <sup>CV</sup>	degree <sup>max</sup> ( $D^T$ )	degree <sup>CV</sup>
$D_{\text{empty}}$	1	0	0	1	$n$	0	0	0
$D_{\text{complete}}$	$n$	$\frac{n^2}{2}$	$n$	0	1	0	2	$\frac{1}{\sqrt{2n}}$
$D_{\text{chain}}$	$n$	$n$	$n$	0	1	0	2	$\frac{1}{\sqrt{2n}}$
$D_{\text{out-tree}}$	$\log_2(n)$	$n$	$n$	1	$\frac{n}{\log_2(n)}$	$\sqrt{\frac{\log_2(n+1)}{3}}$	3	$\frac{1}{2}$
$D_{\text{in-tree}}$								
$D_{\text{comb}}$	$\frac{n}{2}$	$n$	$n$	1	2	$\frac{1}{\sqrt{2n}}$	3	$\frac{1}{2}$
$D_{\text{comb}}^R$	$\frac{n}{2}$	$n$	$n$	$\frac{1}{2}$	2	$\sqrt{\frac{n}{8}}$	3	$\frac{1}{2}$
$D_{\text{bipartite}}$	2	$\frac{n^2}{4}$	$\frac{n^2}{4}$	1	$\frac{n}{2}$	0	$\frac{n}{2}$	0
$D_{\text{square}}$	$\sqrt{n}$	$n\sqrt{n}$	$n\sqrt{n}$	1	$\sqrt{n}$	0	$2\sqrt{n}$	$\frac{1}{\sqrt{2\sqrt{n}}}$
$D_{\text{triangular}}$	$\sqrt{2n}$	$\frac{2n\sqrt{2n}}{3}$	$\frac{2n\sqrt{2n}}{3}$	1	$\sqrt{\frac{n}{2}}$	$\frac{1}{\sqrt{3}}$	$2\sqrt{2n}$	$\frac{1}{2\sqrt{2}}$



## Selected DAGs Properties

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length easy instance when small or large

$m$  number of edges

$m(D^T)$  number of non-redundant edges

mass size of largest sub-problem

mean shape close to the width

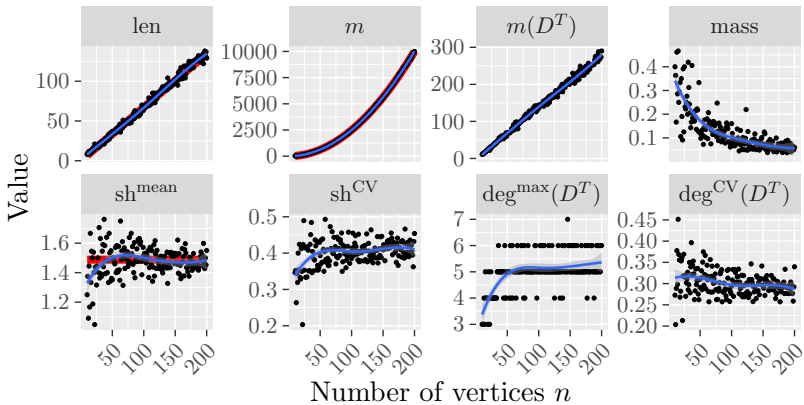
shape CV indicate how the shape varies

max degree measure local to a single vertex

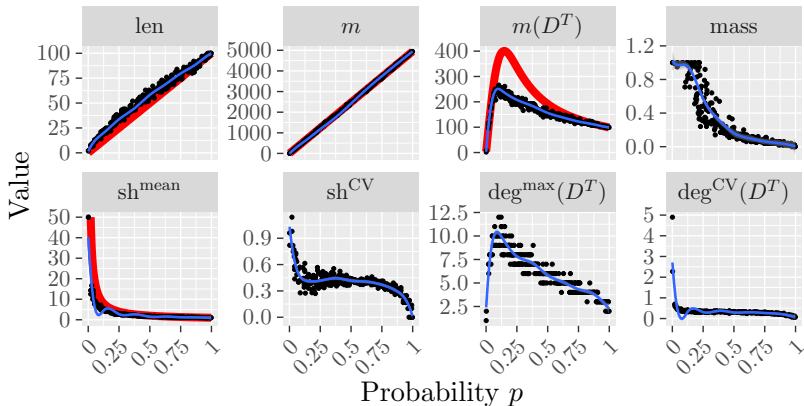
degree CV indicate how the degrees vary



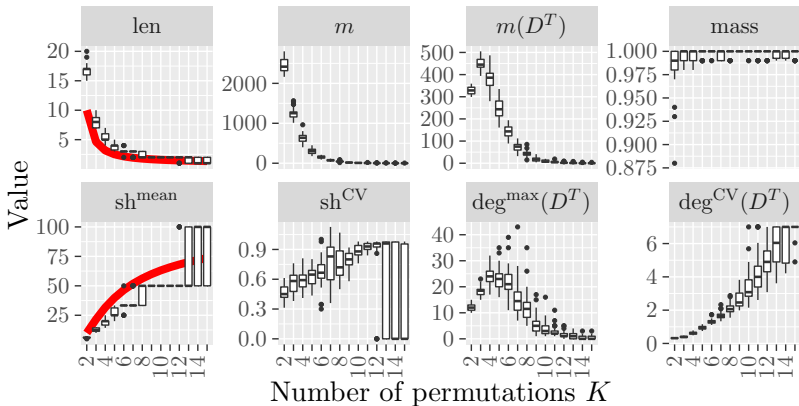
# Uniform Analysis



# Erdős-Rényi Analysis

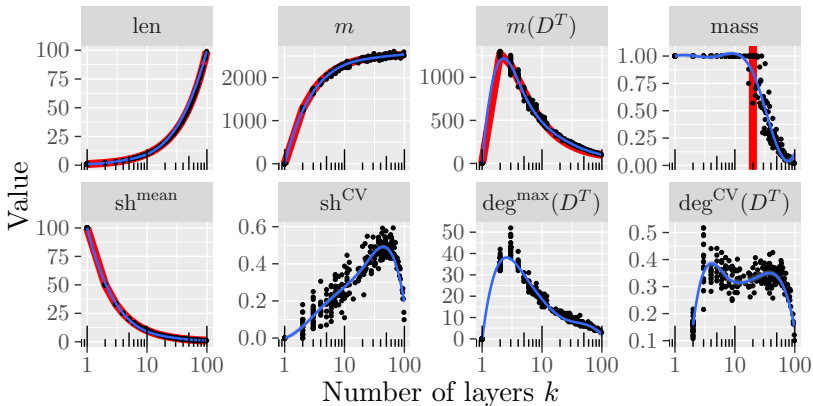


# Random Order Analysis





## Layer-by-Layer Analysis





## Conclusion

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### Summary:

- ▶ analyse several DAG properties (e.g. mass)
- ▶ provide formal and empirical analysis of existing random generators
- ▶ establish the sub-exponential generic time complexity with uniform DAGs

### Perspectives:

- ▶ generalize properties to non-unitary costs and communications
- ▶ design generator uniform on a relevant subspace